

An Analysis of the Blue Noise Mask Based on a Human Visual Model

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ABSTRACT

The Blue Noise Mask (BNM) is a stochastic screen that produces visually pleasing blue noise. In its construction, a

$$\begin{aligned}
E'^2 &= \sum_{i=0}^{N-1} \sum_{j=0}^{N-1} \left[f(i, j) + h\left((i - i_0)_{\text{mod } N}, (j - j_0)_{\text{mod } N}\right) - g' \right]^2 \\
&= \sum_{i=0}^{N-1} \sum_{j=0}^{N-1} \left[f(i, j) - g' \right]^2 + \sum_{i=0}^{N-1} \sum_{j=0}^{N-1} h^2\left((i - i_0)_{\text{mod } N}, (j - j_0)_{\text{mod } N}\right) \\
&\quad + 2 \sum_{i=0}^{N-1} \sum_{j=0}^{N-1} f(i, j) h\left((i - i_0)_{\text{mod } N}, (j - j_0)_{\text{mod } N}\right) \\
&\quad - 2 \sum_{i=0}^{N-1} \sum_{j=0}^{N-1} g' h\left((i - i_0)_{\text{mod } N}, (j - j_0)_{\text{mod } N}\right)
\end{aligned}$$

$i=0 \ j=0$

(8)

There are four terms on the right side of the above equation. Since g' is a constant and $f(i, j)$ is known, the first term in equation (8) is fixed. The second term is a summation of the shifted filter squared over the support of the BNM. Due to the "wrap-around" property, this term is constant. For the same argument, the fourth term is also a constant. Let

$$G(i_0, j_0) = \sum_{i=0}^{N-1} \sum_{j=0}^{N-1} f(i, j) h\left((i - i_0)_{\text{mod } N}, (j - j_0)_{\text{mod } N}\right)$$

(9)

$i=0 \ j=0$

where $G(i_0, j_0)$ is a function of i_0 and j_0 . It follows that minimizing E'^2 is reduced to minimizing $G(i_0, j_0)$.

Substituting (3) into (9) we have:

$$G(i_0, j_0) = \sum_{j=0}^{N-1} \sum_{i=0}^{N-1} \sum_{m=0}^{N-1} \sum_{n=0}^{N-1} h\left((i - m)_{\text{mod } N}, (j - n)_{\text{mod } N}\right) b(m, n) h\left((i - i_0)_{\text{mod } N}, (j - j_0)_{\text{mod } N}\right)$$

(10)

$$R(m, n, i_0, j_0) = \sum_{k=0}^{N-1} \sum_{l=0}^{N-1} h(k, l) h\left(\left(k + (m - i_0)\right)_{\text{mod } N}, \left(l + (n - j_0)\right)_{\text{mod } N}\right) \quad (15)$$

which is the circular autocorrelation (for simplicity, we will use "autocorrelation" for "circular autocorrelation" from now on) of h at $(m - i_0, n - j_0)$ and can be denoted as $R_h\left(\left(m - i_0\right)_{\text{mod } N}, \left(n - j_0\right)_{\text{mod } N}\right)$. Substituting into (11) and making use of the symmetry of the autocorrelation function, we obtain:

$$G(i_0, j_0) = \sum_{m=0}^{N-1} \sum_{n=0}^{N-1} b(m, n) R_h\left(\left(i_0 - m\right)_{\text{mod } N}, \left(j_0 - n\right)_{\text{mod } N}\right) \quad (16)$$

In the frequency domain, R_h corresponds to $|H|^2$. It can be easily seen that $G(i_0, j_0)$ is the circular convolution of the binary pattern for level g with a new filter that is the autocorrelation function of h .

Examination of equation (11) tells us that to minimize $G(i_0, j_0)$, or the perceived error for level g' measured by the

Let's examine how we can find the P black points in $f(i,j)$ which, when converted to white, will minimize E^2 , or $G(i_0, j_0)$. To minimize the first term of $G(i_0, j_0)$, we use the autocorrelation function R_h of h as a filter and apply it